1. Introduction

Heating, Ventilation and Cooling (HVAC) is the single biggest cause to a home's energy bills and carbon outflows, representing 43% of private energy utilization in the U.S. furthermore, 61% in Canada and the U.K., which have colder atmospheres\(^1\). Studies have demonstrated that 20-30% of this energy could be spared by stopping the HVAC system when occupants are resting or away. A 20-30% lessening in HVAC energy would mean funds of about $15 every month for the normal family in the U.S. For some individuals, this little money related sparing does not legitimize the troubles of streamlining HVAC operation on a consistent schedule. At the national scale\(^2\), on the other hand, these same investment funds mean more than 100 Billion kWh at an expense of roughly $15 billion every year, and would forestall roughly 1.12 billion tons of contaminations from being discharged into the air every year. It is an exemplary disaster of the center.

To address this circumstance, another arrangement must be made that “just works” and spares energy without needing every day thought or activity by family members. An answer for this issue are the smart thermostats\(^3\), \(^4\) that uses inbuilt sensors to naturally stop the HVAC framework when the tenants are dozing or away from home. The basic function for the thermostat is to set the temperature and control the HVAC system to maintain the current temperature to reach the set temperature. A second and expanding role is to spare energy. Numerous new highlights and capacities have risen in the previous a quarter century encourage the energy saving. The most propelled thermostat control various zones and humidity...
levels. Still different highlights incorporate one-touch energy-savings, diagnostics, access to weather, alerts for maintenance and display of energy consumption. Remote control is turning into a famous highlight as advanced mobile phones and Internet access. Expanded comfort is achieved by having the limit of the HVAC framework\(^5\) (cooling or warming conveyed) take after the shift in burden as it changes over the house. For instance, it is regular for two-stored homes to be excessively hot on the second floor in both summer and winter. Zoning has the capacity of occupying a greater amount of the HVAC ability to the territory with the higher burden\(^6\). Another regular case is a home with a noteworthy zone of west-bound and east-bound windows. In the late spring, the east rooms overheat in the morning and the west rooms overheat toward the evening.

Starting 2014, Z-Wave is bolstered by more than 250 makers overall and shows up in an expansive scope of consumer and business items in the US, Europe and Asia. The lower layers, MAC and PHY, are portrayed by ITU-T G.9959 and completely in reverse perfect. The Z-Wave handset chips are supplied by Sigma Designs and Mitsumi. Below are the few of the advantages of Z-wave:

- secure and reliable communication
- low power utilization
- simple installation
- local or remote control
- various accessible devices, interoperability

The Figure 2 shows the applications of the Z-wave wireless network.

![Figure 1. Zoning system.](image)

2. Research Method

The Figure 3 shows the wireless sensor unit and the Figure 4 shows the complete design of the controller unit. The wireless sensor unit contains the sensor, the microcontroller unit and the Z-wave device. The controller unit contains the Z-wave device, microcontroller, display unit and the HVAC unit. In the wireless sensor unit, the sensor is RHT03 which is a humidity and temperature sensor. It communicates using Max detect 1-wire bus protocol.

![Figure 2. Z-wave network.](image)

![Figure 3. Block diagram of the wireless sensor unit.](image)
Figure 4. Block diagram of the controller unit.

The microcontroller has a free RTOS which has tasks that receives data from the sensor every 30 sec and sends the information to the Z-wave device. The microcontroller communicates to the Z-wave device using UART or USB. The Z-wave device then sends the information to the controller in whose network it exists. Z-wave controller sends the information sent by the controller to the microcontroller unit using UART or USB in the controller unit. The microcontroller based on the temperature value takes decision to control the HVAC system to maintain the desired set point. The microcontroller also sends information to display it on the display unit.

2.1 Sensor

RHT03\(^{11}\) is a temperature and relative humidity measurement sensor. It has high precision, capacitive type, calibrated digital signal output. It is a small size, low power, long term stable and has long transmission distance up to 100m. The calibration coefficients are stored in the OTP memory, which are used every time a sensor values is used. The Table 1 shows the pin details of the sensor RHT03.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>VDD</td>
<td>Supply voltage</td>
</tr>
<tr>
<td>2</td>
<td>DATA</td>
<td>Signal</td>
</tr>
<tr>
<td>3</td>
<td>NULL</td>
<td>Not Connected</td>
</tr>
<tr>
<td>4</td>
<td>GND</td>
<td>Ground</td>
</tr>
</tbody>
</table>

2.1.1 Pins and Power (VDD)

The supply voltage to the sensor is 3.6-6 V. It is expected to put a coupling capacitor of 100mF between the supply pins and the ground as shown in Figure 5.

Figure 5. Pin diagram of RHT03.

Signal and communication: For the communication between the sensor and the microcontroller MaxDetect-1 wire bus. The communication between the sensor and the microcontroller starts with a start signal, which is a transition from high to low signal. After this the microcontroller pulls the line high waiting for the sensor to respond. The response is sent from the sensor by pulling the line low and the sensor gets ready to send the 40 bit values. The 40 bit value has the relative humidity, temperature and the check sum.

The first 16 bit of the 40 bit has the relative humidity which is again divided into 8 bit of integral RH data and 8 bit of decimal RH data. The next 16 bits of the 40 bit data is the temperature value which is again divided into 8 bit of integral temperature data and 8 bit of decimal temperature data. The next 8 bit of the 40 bit is the checksum value which is the sum of all the 32 bits that are sent before. The time interval of the whole process must be more than 2 seconds.

2.1.2 MaxDetect 1-wire Bus

Data is comprised of integral and decimal part; the following is the formula for data.

The data that is received consists of the decimal part and the integral part. Below is the formula that shows how the data is divided

\[
\text{DATA} = 8 \text{ bit integral Relative humidity data} + 8 \text{ bit decimal Relative humidity data} + 8 \text{ bit integral Temperature data} + 8 \text{ bit decimal Temperature data} + 8 \text{ bit check}
\]

The check sum is calculated as

\[
\text{Check sum} = 8 \text{ bit integral Relative humidity data} + 8 \text{ bit decimal Relative humidity data} + 8 \text{ bit integral Temperature data} + 8 \text{ bit decimal Temperature data}
\]

If the transmission is right then the received checksum and the calculated check sum after reception of all the bits should be correct.
Example: Microcontroller Unit has received 40 bits data from sensor RHT03 as

\[
\begin{array}{ccc}
0000 & 0000 & 0000 \\
0001 & 0111 & 1110 \\
0000 & 0000 & 0001 \\
1001 & 1001 & 1000 \\
\end{array}
\]

RH data T data Check Sum

Check sum = 0000 0001+0111 1110+0000 0000+0001 1001 = 10011000
RH = (0000 0000 0001 1001)/10 = 38.2%RH
T = (0000 0000 0001 1001)/10 = 25ºC

When MSB of temperature is 1, it means the temperature is below 0 degree Celsius.

Example: 1000 0000 0110 0101, T = minus 10.1ºC.

The sensing element in the sensor is a polymer humidity capacitor. It operation range of the sensor for humidity is from 0-100 % RH and for the temperature is -40 to 80 ºCelsius. The sensitivity of the sensor is 0.1% RH for humidity and 0.1 ºC for the temperature.

### 2.2 Host Microcontroller unit

The LPC1115 LPCXpresso board with NXP’s ARM Cortex-M0 microcontroller has been intended to make it as simple as could reasonably be expected to begin with Cortex-M0. The LPCXpresso embodies a target board joined with a JTAG debugger. The LPC1115 has 8 kB SRAM, 64 kB Flash, SSP, I2C, UART, ADC and so on. The Figure 6 shows the LPC1115 LPCXpresso board.

![Figure 6. LPC1115 LPCXpresso board.](image)

The microcontroller receives the temperature value and sends it to the z-wave device using UART or USB. On the implementation there are different tasks which used for the proper functioning of the device. One task performs the job of receiving the data from the sensor. The other task performs sending the data to the Z-wave device and waiting for the data that can be received from the z-wave device. Semaphores are used for data synchronization. Inter process communication happens through message queues. The data from the microcontroller to the Z-wave device is sent in a specific format as per the serial API.

### 2.3 Z-wave

Z-wave microcontroller is constructed around an upgraded 8051 microcontroller center that runs off a 32MHz external oscillator. (The inner framework clock is 16MHz). The RF a piece of the chip contains a FSK handset for a 908.42MHz or 868.42MHz recurrence that is programming selectable. The advanced piece of the IC comprises of 32KB of FLASH memory, 2KB of SRAM and a modest bunch of control-driven peripherals. With force supply somewhere around 2.2 and 3.6 volts, it expends 23mA in transmit mode (about -5dBm) and 21mA and 3A separately in get and profound slumber modes. MCU peripherals comprise of standard modules like SPI, clocks, UART, External interrupt and brownout recognition and in addition particular modules for control applications: 12-bit ADC (simple to computerized converter) and upgraded TRIAC control with zero intersection identification line. Ten GPIO lines are multiplexed with other I/O capacities.

The Z-wave micro communicates with the host microcontroller using UART or USB. The device is then sent to the Z-wave controller using the appropriate command classes. The device has to be configured as a routing multilevel sensor device class. Based on the command classes sent the controller sends it to the microcontroller to which it is connected to. Before sending the values the device has to get included to the network with proper inclusion process and to remove the device from the network proper exclusion process should happen.

### 2.4 Microcontroller and Display Unit

An ARM based microcontroller is used at the controller. It provides low-power solutions for applications demanding high-performance multimedia and graphics. It can be interfaced through I2C, UART, CAN and USB. The display contains TFT color display, together with a PCAP touch panel on top provides the main user interface. It runs on a Linux platform.

This microcontroller has pthreads implemented which runs parallel to take care of all the functions of the microcontroller. The microcontroller receives the sensor value from the Z-wave controller using UART or USB. There are different pthreads which works to display
the temperature and humidity on the home screen of the thermostat. Based on the values that are set on the thermostat and the current values from the sensor the necessary actions will be taken to control the HVAC system. The actions will be turning on/off the heating or the cooling system of the particular zone. The Zone can be associated to the Z-wave device with the Node ID. Every time a device gets added to the network a node ID is assigned to it by the controller which is used for this association.

The temperature and humidity values are displayed on the display unit. The microcontroller talk to the application is a predefined data exchange format. The connection between the microcontroller and the application is through Socket connection.

3. Results

The Figure 7 below shows the humidity value that is read from the sensor to the microcontroller. It shows that the received humidity value is 38% RH. Similarly the Figure 8 shows the temperature value that is read which is 25°C.

![Figure 7. Screenshot humidity value.](image)

The Figure 9 and 10 shows the temperature and the humidity difference from the on board sensor and the Z-wave sensor. It is observed that the Z-wave sensor output is more accurate.

As per the work in the paper by Bassam Shaer\(^1\), the Zigbee based wireless sensor had a few drawbacks like the increase in cost because of the use of ADC and also the range of 100 ft. was not achieved in reality. Seeing these parameters Z-wave can be a possible solution for the design of a wireless sensor that can be associated to each zone in the Zoning system. Since Z-wave has a lesser frequency than Zigbee it can achieve higher range than Zigbee. Below are the few parameters which show that Z-wave is better that Zigbee for this application. The Table 2 shown below shows a comparison between the two wireless technologies Z-wave and Zigbee.

![Figure 10. Screen shot of temperature value in °C.](image)

**Table 2. Comparison table**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Zigbee</th>
<th>Z-wave</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frequency</td>
<td>2.4 Ghz</td>
<td>900Mhz</td>
</tr>
<tr>
<td>Range</td>
<td>10m</td>
<td>30m</td>
</tr>
<tr>
<td>Battery life</td>
<td>100+ days</td>
<td>100+ days</td>
</tr>
<tr>
<td>Network size</td>
<td>65536</td>
<td>232</td>
</tr>
<tr>
<td>Data rate</td>
<td>250 kbits/sec</td>
<td>100kbits/sec</td>
</tr>
</tbody>
</table>
4. Conclusion

In this research work, the wireless sensor for a single zone is implemented. The controller can have a network size of 232. Hence, many wireless sensors can be added to the networks which are associated with different zones. The sensor reports the temperature and humidity value every 30 sec. The power consumption can be reduced by decreasing the time interval or sending only when value changes and put the device to sleep when it is not processing. Since the Z-wave devices can achieve 4 hops, greater range can be obtained by having a repeater in the network. This works provides solution to avoid the hard wires to install sensors in zoning system and it also proves a possible solution for the inaccuracy in the temperature and humidity values that are detected by the onboard sensors.

5. Acknowledgement

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6. References

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